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NAVAL WEAPONS CENTER CHINA LAKE CALIF  
TEST PROCEDURE - LINEAR EQUATION ROUTINES.(U)

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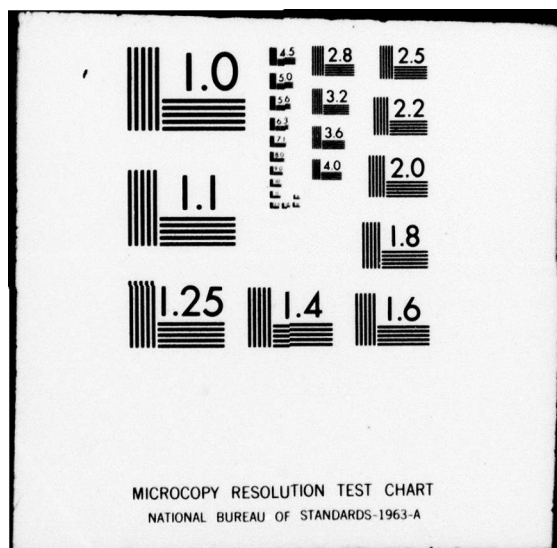
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by  
10 L. W. Lucas  
Research Department  
11 March 1975  
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China Lake, California 93555

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The general test procedure is to apply each candidate routine to a number of test problems (with known answers) and to record the resulting accuracy and execution time. It is assumed that each candidate routine can solve the problem

$$AX=B$$

where:

A is a general  $n \times n$  coefficient matrix,

B is a general  $n \times m$  right-hand-side matrix, and

X is an  $n \times m$  solution matrix.

If B is set equal to the  $n \times n$  identity matrix I (so that  $m = n$ ), then X will be an approximation to  $A^{-1}$ . The accuracy achieved can be measured by computing the norm of the residual matrix

$$R = AX - I \quad (\text{or} \quad R = XA - I) \quad 1/A$$

or better, by computing the norm of the error matrix

$$E = X - A^{-1} \quad 1/A$$

the first equation

This approach is used in order to avoid having to solve Eq. (1) repeatedly using various right-hand sides B for each test matrix A. Execution time is measured by the system clock.

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# FOREWORD

This work was done in connection with the author's position as Numerical Mathematics Coordinator, Central Computing Facility (CCF) and was supported by CCF funds. The actual testing of routines under the procedure outlined here is continuing. This is a preliminary report, subject to revision or withdrawal, and is not to be used as the basis for official action.

D. E. ZILMER  
Head, Mathematics Division  
Research Department  
31 March 1975

NWC TM 2410, published by Code 607, 50 copies.

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DUB	Dark Section <input type="checkbox"/>
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# CONTENTS

Introduction . . . . .	1
Error Measures . . . . .	1
Test Output . . . . .	3
Test Matrices . . . . .	3
Wilkinson Matrix . . . . .	4
Hilbert Matrix . . . . .	4
Newman-Todd Matrix . . . . .	5
Rutishauser Matrix . . . . .	6
Pei Matrix . . . . .	6
Givens Matrix . . . . .	7
Appendixes:	
A. Matrix Norms and Condition Numbers . . . . .	9
B. Program Package for Testing Linear Equation Routines . . . . .	13
FNORM . . . . .	15
LEQTST . . . . .	17
LTERR . . . . .	19
LTEST . . . . .	21
LTGIVN . . . . .	23
LTHILB . . . . .	25
LTNEWT . . . . .	27
LTPEI . . . . .	29
LTPRNT . . . . .	31
LTRITE . . . . .	33
LTRUTH . . . . .	35
LTWILK . . . . .	37
MXRITE . . . . .	39
References . . . . .	40

4

## INTRODUCTION

The general test procedure is to apply each candidate routine to a number of test problems (with known answers) and to record the resulting accuracy and execution time. It is assumed that each candidate routine can solve the problem

$$AX = B \quad (1)$$

where

$A$  is a general  $n \times n$  coefficient matrix

$B$  is a general  $n \times m$  right-hand-side matrix

$X$  is an  $n \times m$  solution matrix

If  $B$  is set equal to the  $n \times n$  identity matrix  $I$  (so that  $m = n$ ), then  $X$  will be an approximation to  $A^{-1}$ . The accuracy achieved can be measured by computing the norm of the residual matrix

$$R = AX - I \quad (\text{or} \quad R = XA - I)$$

or better, by computing the norm of the error matrix

$$E = X - A^{-1}$$

This approach is used in order to avoid having to solve Eq.(1) repeatedly using various right-hand sides  $B$  for each test matrix  $A$ . Execution time is measured by the system clock.

## ERROR MEASURES

Measures of error used in previous studies of linear equation routines [4,5] are<sup>1</sup>

---

<sup>1</sup> See Appendix A for definitions of the matrix norms  $\|\cdot\|_S$ ,  $\|\cdot\|_F$ ,  $\|\cdot\|_M$ ,  $\|\cdot\|_\infty$ .



$$a = \frac{1}{n^2} \|R\|_S \quad [4,5]$$

$$f = \frac{1}{n} \|R\|_F \quad [4,5]$$

$$m = \frac{1}{n} \|R\|_M \quad [5]$$

$$q = \frac{1}{n^2} \|E\|_S \quad [4]$$

Newman and Todd [5] caution that matrices  $A$  and  $X$  exist for which  $AX - I$  is almost 0 while elements of  $XA - I$  are arbitrarily large. In their tests  $AX - I$  and  $XA - I$  varied by as much as three orders of magnitude. Lietzke et al. [4] report that

1.  $a \leq f$  for each test matrix and each routine tested.
2.  $a$  and  $f$  are not reliable estimators of  $q$ .
3. The following estimator for  $\|E\|_\infty$  seems to work for well-conditioned matrices:

$$\ell = \frac{\|XR\|_\infty}{1 - \|R\|_\infty}$$

where  $R = AX - I$ .

Measures of error recommended here are listed below. The Frobenius norm is recommended, since (like the Euclidean matrix norm) it is compatible with the Euclidean vector norm and invariant under unitary transformations.

<u>Type of Error</u>	<u>Computation</u>
Actual relative error	$\frac{\ E\ _F}{n\epsilon \ A^{-1}\ _F}$
Actual absolute error	$\frac{1}{n\epsilon} \ E\ _F$
Estimated absolute error	$\frac{\ XR\ _F}{n\epsilon(1 - \ R\ _F)}$
Residual error	$\frac{1}{n\epsilon} \ R\ _F$

where  $E = X - A^{-1}$  and  $R = AX - I$ . The above calculations must be done in double precision.

## TM 2410

The infinity norm may also be used--as a check on the computations, and to test the conjecture of Lietzke et al. The normalization factor  $\frac{1}{\epsilon}$  (where  $\epsilon = 2^{-26} \cong 1.5 \times 10^{-8}$  is the single-precision machine 'infinitesimal' on UNIVAC 1100 Series computers) is used to scale calculated errors to unity. The normalization factor  $\frac{1}{n}$  is used to scale the calculated errors to the same units as the elements of the error matrix.

## TEST OUTPUT

For each candidate routine and each test matrix the following summary output is needed.

- Heading identifying routine
- Name of test matrix
- Order of test matrix
- Value of error return flag
- Time for solution
- Logarithm of condition number of test matrix
- Actual relative error
- Actual absolute error
- Estimated absolute error
- Residual error

In addition, the following detailed output should be available upon request.

- Test matrix  $A$
- Calculated inverse  $X$
- Exact inverse  $A^{-1}$
- Error matrix  $E = X - A^{-1}$
- Residual matrix  $R = AX - I$

## TEST MATRICES

The test matrices recommended for use are listed below, together with a summary of their properties. These test matrices were culled from [3,7]. Each family of test matrices (except Wilkinson) is defined for any order  $n$ . The test matrices and their exact inverses are easily computed. The test matrices (except Newman-Todd) all have integer elements and span the range from well-conditioned to very ill-conditioned. One family (the Pei matrices) have a parameter that allows one to vary the condition number. Subroutines for generating the test matrices and their inverses are documented in Appendix B.



Matrix	$n$	Condition <sup>a</sup>	Form
Wilkinson	6	good	nonsymmetric
inverse Hilbert <sup>b</sup>	small	very bad	symmetric
Newman and Todd <sup>b</sup>	all	good	orthogonal, symmetric
Rutishauser <sup>b</sup>	small	very bad	lower triangular
Pei <sup>c</sup>	all	variable	symmetric and positive definite
Givens <sup>b</sup>	all	fair	symmetric and positive definite

<sup>a</sup> Precise condition numbers are given in Appendix A.

<sup>b</sup> Used in study by Newman and Todd [5].

<sup>c</sup> Used by Newman and Todd [5] for  $a = n$  and by Lietzke et al. [4] for  $a = 1$ .

#### Wilkinson Matrix

This matrix (#3.4 in [3]) is for initial program checkout. It is well-conditioned and nonsymmetric.

$$W = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 & -1 \\ -1 & 1 & 1 & 0 & 0 & 1 \\ 1 & -1 & 1 & 1 & 0 & -1 \\ -1 & 1 & -1 & 1 & 1 & 1 \\ -1 & -1 & 1 & -1 & 1 & -1 \end{bmatrix}$$

$$W^{-1} = \frac{1}{32} \begin{bmatrix} 16 & 8 & -4 & 2 & -1 & 1 \\ 0 & 16 & 8 & -4 & 2 & -2 \\ 0 & 0 & 16 & 8 & -4 & 4 \\ 0 & 0 & 0 & 16 & 8 & -8 \\ 0 & 0 & 0 & 0 & 16 & 16 \\ 16 & -8 & 4 & -2 & 1 & -1 \end{bmatrix}$$

#### Hilbert Matrix

These matrices (#3.8 in [3]) are very ill-conditioned. The Hilbert matrix  $H_n$  of order  $n$  is defined by

$$H_n = (h_{ij})$$

where

$$h_{ij} = \frac{1}{i+j-1} \quad (i, j = 1, 2, \dots, n)$$

Because they are so badly conditioned, Hilbert matrices are often used to test matrix inversion routines. But this must be done properly. Inverses of the Hilbert matrices  $T_n = H_n^{-1}$  are used as the test matrices, since all elements of  $T_n$  are integers. Reference [3] lists the inverse Hilbert matrices  $T_n$  for  $n = 2, 3, \dots, 10$ . For testing purposes it probably suffices to try  $n = 3, 5$ , and  $7$ . Integer overflow will occur on the UNIVAC 1110 for  $n = 8$ . Some facts about Hilbert matrices, based on information in [2], are summarized below. Here  $C_2(H_n)$  denotes the  $\ell_2$  condition number of  $H_n$  (see Appendix A) and  $\ell(T_n)$  denotes the largest element of  $T_n$ .

Facts About Hilbert Matrices

$n$	$C_2(H_n)$	$\ H_n\ _2$	$\ T_n\ _2$	$\ell(T_n)$
2	1.93(+1)	1.27	1.52(+1)	1.20(+1)
3	5.24(+2)	1.41	3.72(+2)	1.92(+2)
4	1.55(+4)	1.50	1.03(+4)	6.48(+3)
5	4.77(+5)	1.57	3.04(+5)	1.79(+5)
6	1.50(+7)	1.62	9.24(+6)	4.41(+6)
7	4.75(+8)	1.66	2.86(+8)	1.33(+8)
8	1.53(+10)	1.70	9.00(+9)	4.25(+9)
9	4.93(+11)	1.73	2.86(+11)	1.22(+11)
10	1.60(+13)	1.75	9.15(+12)	3.48(+12)

#### Newman-Todd Matrix

These matrices (#3.11 in [3]) are orthogonal and symmetric, but not positive definite. They are defined by

$$A_n = (a_{ij}), \quad a_{ij} = \sqrt{\frac{2}{n+1}} \sin \frac{ij\pi}{n+1}$$

These matrices are well-conditioned, but costly to generate (because of calls to DSIN and DSQRT).

Rutishauser Matrix

These matrices (#3.15 in [3]) are ill-conditioned and lower triangular. They are defined by

$$R_n = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & \dots & 0 \\ 1 & -1 & 0 & 0 & 0 & \dots & 0 \\ 1 & -2 & 1 & 0 & 0 & \dots & 0 \\ 1 & -3 & 3 & -1 & 0 & \dots & 0 \\ 1 & -4 & 6 & -4 & 1 & & \\ \cdot & \cdot & \cdot & \cdot & & \cdot & \\ \cdot & \cdot & \cdot & \cdot & & \cdot & \\ \cdot & \cdot & \cdot & \cdot & & \cdot & \\ 1 & -n+1 & & & & & (-1)^{n-1} \end{bmatrix}$$

The elements of  $R_n$ , except for sign, are the numbers in Pascal's triangle, that is, binomial coefficients.  $R_n$  is its own inverse.

Pei Matrix

The Pei matrices ([3, p. 18] and #18 in [7]) are symmetric and positive definite. They are defined by

$$P_n(a) = (p_{ij}), \quad p_{ij} = \begin{cases} a + 1 & i = j \\ 1 & i \neq j \end{cases}$$

where  $a > 0$ . Note that as  $a \rightarrow 0$ ,  $P$  becomes singular. Eigenvalues of  $P$  are  $\lambda = a + n$  (simple) and  $\lambda = a$  (multiplicity  $n - 1$ ). Thus, for  $a \cong n$ ,  $P_n$  is well-conditioned; but for  $a \cong 0$ ,  $P_n$  is very ill-conditioned.

Recommended choices of the Pei parameter  $a$  are

$$a = 64\epsilon, 1, n$$

where  $\epsilon = 2^{-26} \cong 1.5 \times 10^{-8}$ .

To compute the inverse of  $P_n(a)$ , let  $J$  be the matrix with all elements equal to 1. Then (dropping the subscript  $n$ )

$$P = aI + J.$$

10



Since  $J^2 = nJ$ , we expect  $P^{-1} = Q$  to be linear in  $J$ ,

$$Q = bI + cJ.$$

Computing the product  $PQ$  we find

$$I = PQ = (aI + J)(bI + cJ) = abI + (b + ac + nc)J.$$

Equating coefficients,

$$\left. \begin{array}{l} ab = 1 \\ b + ac + nc = 0 \end{array} \right\} \Rightarrow \begin{array}{l} b = \frac{1}{a} \\ c = -\frac{b}{a+n} = -\frac{1}{a(a+n)}. \end{array}$$

Hence,

$$Q = \frac{1}{a} \left( I - \frac{1}{a+n} J \right)$$

or

$$P^{-1} = (q_{ij}), \quad q_{ij} = \begin{cases} \frac{a+n-1}{a(a+n)} & i = j \\ -\frac{1}{a(a+n)} & i \neq j. \end{cases}$$

#### Givens Matrix

The Givens matrices (#8 in [7]) are poorly-conditioned, symmetric, and positive definite. They are defined by

$$G_n = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & 3 & 3 & \dots & 3 \\ 1 & 3 & 5 & \dots & 5 \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ 1 & 3 & 5 & \dots & 2n-1 \end{bmatrix}$$

Thus,  $G_n = (g_{ij})$  where  $g_{ij} = 2 \min(i, j) - 1$ . The inverse is given by

TM 2410

$$G_n^{-1} = \frac{1}{2} \begin{bmatrix} 3 & -1 & & & & & & & 0 \\ -1 & 2 & -1 & & & & & & \\ & -1 & 2 & . & & & & & \\ & & -1 & . & . & & & & \\ & & & . & . & . & & & \\ & & & & . & . & -1 & & \\ 0 & & & & & . & 2 & -1 & \\ & & & & & -1 & 1 & & \end{bmatrix}$$

Note that the inverse Givens matrix is tridiagonal.



# Appendix A.

## MATRIX NORMS AND CONDITION NUMBERS

The more common matrix and vector norms are defined here, without much explanation. For a more complete discussion of matrix and vector norms and their properties, see [1,6]. Vector norms in common use are

$$\|x\|_1 = \sum_i |x_i|$$

$$\|x\|_2 = \sqrt{\sum_i x_i^2} \quad (\text{Euclidean})$$

$$\|x\|_\infty = \max_i |x_i| \quad (\text{Chebyshev}).$$

These are particular instances of the  $p$ -norm

$$\|x\|_p = \sum_i |x_i|^p.$$

Any vector norm induces a matrix norm according to the following relation:

$$\|A\| = \max_{\|x\|=1} \|Ax\| \quad (\text{A.1})$$

where the maximum is taken over all  $x$  such that  $\|x\| = 1$ . Matrix norms induced in this way are compatible with the underlying vector norm, in the sense that

$$\|Ax\| \leq \|A\| \cdot \|x\| \quad (\text{for all } x).$$

The matrix norms induced by the vector  $p$ -norms ( $p = 1, 2, \infty$ ) are

$$\|A\|_1 = \max_j \sum_i |a_{ij}| \quad (\text{column sum})$$

$$\|A\|_2 = \sqrt{\text{largest eigenvalue of } A^T A} \quad (\text{Euclidean})$$

$$\|A\|_\infty = \max_i \sum_j |a_{ij}| \quad (\text{row sum})$$

Matrix norms, besides those induced by vector  $p$ -norms, are also used. Among the most useful are

$$\|A\|_S = \sum_i \sum_j |a_{ij}| \quad (\text{sum norm})$$

$$\|A\|_F = \sqrt{\sum_i \sum_j a_{ij}^2} \quad (\text{Frobenius norm})$$

$$\|A\|_M = n \max_i \max_j |a_{ij}| \quad (\text{max norm}).$$

It is easily proven that  $\|A\|_S$  is compatible with  $\|x\|_1$ , that  $\|A\|_F$  is compatible with  $\|x\|_2$ , and that  $\|A\|_M$  is compatible with  $\|x\|_\infty$ . Also,

$$\frac{1}{n} \|A\|_S \leq \|A\|_\infty \leq \|A\|_M \leq n \|A\|_S$$

$$\frac{1}{n} \|A\|_S \leq \|A\|_1 \leq \|A\|_M \leq n \|A\|_S$$

so that the choice of a norm is not too critical in finite-dimensional linear spaces (that is, for matrices).

The condition number of a matrix for a given matrix norm is defined by

$$c(A) = \|A\| \cdot \|A^{-1}\|. \quad (\text{A.2})$$

From this definition it is clear that  $c(A^{-1}) = c(A)$ . The condition number recommended in this report is derived from the Frobenius matrix norm

$$c_F(A) = \|A\|_F \cdot \|A^{-1}\|_F.$$

The Frobenius condition number should be a good approximation to the Euclidean condition number

$$c_2(A) = \sqrt{\text{largest eigenvalue of } A^T A} / \sqrt{\text{smallest eigenvalue of } A^T A}$$

because of the inequalities

$$\|A\|_2 \leq \|A\|_F \leq \sqrt{n} \|A\|_2.$$

A specialization of the Euclidean condition number, introduced by von Neumann and Goldstine in the early days of computing, is frequently found in the literature (for example, [3]). This condition number is defined by

124

$$c_{\lambda}(A) = \frac{|\text{largest eigenvalue of } A|}{|\text{smallest eigenvalue of } A|}$$

It is sometimes called the 'spectral' condition number, since the spectral radius of  $A$  is the magnitude of the largest eigenvalue of  $A$ . When  $A$  is symmetric, the Euclidean and spectral condition numbers agree

$$c_2(A) = c_{\lambda}(A).$$

Spectral condition numbers for some of the test matrices discussed in this report are given below. These are quoted from [3].

<u>matrix</u>	<u>spectral condition number</u>
Newman-Todd	1
Rutishauser	$\sim e^{4n \ln 2}$
Pei	$1 + \frac{n}{a}$
Givens	$\sim \left(\frac{4n}{\pi}\right)^2$

Condition numbers computed from Eq. (A.2) for various matrix norms will, because of the inequalities relating the matrix norms, all be of the same order of magnitude as the spectral condition numbers quoted above.

For any condition number  $c(A)$ , Forsythe and Moler [2] argue that

$$\log_{10} c(A)$$

is approximately the number of significant digits lost when calculating  $A^{-1}$ . A little arithmetic, based on the condition numbers quoted above, yields the following:



TM 2410

<u>matrix</u>	<u>order</u>	<u><math>\log_{10} c(A)</math></u>
Inverse Hilbert	3	2.72
	5	5.68
	7	7.18
Newman-Todd	all	0
Rutishauser	3	3.61
	5	6.02
	7	8.43
Pei $a = n$	all	0
	$a = 1$	10
		50
		100
	$a = 64\epsilon$	10
		50
		100
	$a = \epsilon$	10
		50
		100
	Givens	10
		50
		100

From the above table it is apparent that condition numbers for families of dense matrices of orders up to several hundred can be classified as follows:

<u>Condition</u>	<u>Functional Form</u>	<u>Example</u>
Good	constant	Newman-Todd, Pei ( $a = n$ )
Fair	linear in $n$	Pei ( $a \cong 1$ )
	quadratic in $n$	Givens
Very bad	exponential in $n$	Rutishauser, Hilbert

Note too that Pei ( $a = 64\epsilon = 2^{-20}$ ) presents a more interesting test problem than Pei ( $a = \epsilon$ ).

16

Appendix B

PROGRAM PACKAGE FOR TESTING LINEAR EQUATION ROUTINES

A program package for testing linear equation routines was written according to the specifications of this report. It consists of the following:

Main Program: LEQTST - overall logic

Subprograms: LTxxxx - generates test matrix and its exact inverse

LTEST - calls candidate routine to calculate inverse and measures execution time

LTERR - computes error matrix, residual matrix and four measures of error

FNORM - returns Frobenius norm of a matrix

LTPRNT - prints summary test results

LTRITE - writes all matrices, if detailed printout requested

MXRITE - writes a single matrix

Program documentation for these program elements is contained in this Appendix, and conforms to the documentation standards of [8].



NAME FNORM

PURPOSE To return Frobenius norm of a matrix

$$\|A\|_F = \sqrt{\sum_i \sum_j a_{ij}^2}$$

USAGE  $F = \text{FNORM}(A, N, NN)$

A.....The matrix - (N, N)	Input
N.....Order of matrix A	Input
NN....Row dimension of A	Input

ACCESS LIB NWC\*MATHLIB.

ERRORS None

REMARKS Although A is single precision, the computation of FNORM is done in double precision.

PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN V
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Certified, Fully Supported by CCF
Entry Names	FNORM
External Refs	DSQRT, NERR3\$
Filename	NWC*MATHLIB
Element/Vers	FNORM
Storage	74 words
Timing	Unknown
Consultant	L. W. Lucas, Ext. 3561

TESTING Output from FNORM was checked against values computed by hand.

REFERENCE NWC TM 2410

NAME LEQTST

PURPOSE To test a linear equation routine by using it to compute inverses  $X$  of test matrices  $A$  having known inverses. The resulting error  $E = X - A^{-1}$  and residual  $R = AX - I$  are used to compute several measures of computational error.

USAGE Main program. There are no inputs to LEQTST. User options involve the setting of three program variables.

NN.....Parameter variable which controls the maximum size of test matrices used.

DETAIL....Logical variable which if .TRUE. causes all matrices involved -  $A$ ,  $X$ ,  $A^{-1}$ ,  $E$ ,  $R$  - to be printed out, as well as summary test information.

IW.....Integer variable which specifies the logical unit number for output.

LEQTST is set up to use the following test matrices.

matrix	order
Wilkinson	6
Inverse Hilbert	3, 5, 7
Newman-Todd	5, 10, 50, 100
Rutishauser	5, 10, 15, 20
Pei, $a = 64\epsilon$	5, 10, 50, 100
$a = 1$	5, 10, 50, 100
$a = n$	5, 10, 50, 100
Givens	5, 10, 50, 100

The maximum order actually used is controlled by the value of  $NN$ .

ACCESS IN 4033519\*NM-BENCH.LEQTST

REMARKS The size of test matrices used in LEQTST is limited only by the available core storage. The design of LEQTST does not provide for buffering to mass storage. LEQTST is not intended to test sparse matrix routines. The test matrices used are believed to be representative of moderately-sized dense matrices.

## PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN V
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Unsupported
Entry Names	None
External Refs	LTHDG, LTWILK, LTEST, LTERR, FNORM, LTPRNT, LTRITE, LTHILB, LTNEWT, LTRUTH, LTPEI, LTGIVN, NINTR\$, ALOG, NSTOP\$
Filename	4033519*NM-BENCH.
Element/Vers	LEQTST
Storage	51080 words (NN = 100)
Timing	103 seconds (NN = 100)
Consultant	None

TESTING The component subprograms for LEQTST were all handchecked.

REFERENCE NWC TM 2410



NAME LTERR

PURPOSE To compute error and residual matrices and four measures of computational error.

USAGE CALL LTERR(A, X, AI, E, R, N, NN, ERR)

A....Test matrix - (N, N)	Input
X....Computed inverse of A	Input
AI...Exact inverse of A	Input
E....Error matrix, $E = X - AI$	Output
R....Residual matrix, $R = AX - I$	Output
N....Order of matrices A, X, AI, E, R	Input
NN...Row dimension of A, X, AI, E, R	Input
ERR..Array of error measures	output

ACCESS IN 4033519\*NM-BENCH.LTERR

ERRORS None

REMARKS Although the arrays A, X, AI, E and R are all single precision, the computations within LTERR are performed in double precision. The measures of error returned in ERR are defined in the reference.

PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Unsupported
Entry Names	LTERR
External Refs	FNORM, DSQRT, NERR3\$
Filename	4033519*NM-BENCH.
Element/Vers	LTERR
Storage	333 words
Timing	unknown
Consultant	None

TESTING Output from LTERR was checked against values computed by hand.

REFERENCE NWC TM 2410

NAME LTEST

PURPOSE To call candidate routine for calculating inverse of test matrix and to measure execution time

USAGE CALL LTEST (A, X, N, NN, TIME, WK, C, IER)

A.....	Test matrix - (N, N)	Input
X.....	Computed inverse of A	Output
N.....	Order of matrices A, X	Input
NN.....	Row dimension of A, X	Input
TIME...	Time to compute inverse	Output
WK.....	Work space of length N*N	Scratch
C.....	Work space - (N, N)	Scratch
IER....	Error return flag	Output

ACCESS IN 4033519\*NM-BENCH.LTEST

ERRORS No errors may occur within LTEST itself. IER returns the value of an error flag from the candidate routine (if any).

REMARKS The input matrix A is copied into the work space C, which is passed to the candidate routine, just in case the routine destroys any coefficient matrix given to it. LTEST will obviously have to be rewritten for each candidate routine tested. SETCLK and LKCLKS are entry points to the system clock routine. LEQT1F is the routine being tested.

PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Unsupported
Entry Names	LTEST
External Refs	SETCLK, LEQT1F, LKCLK, NERR3\$
Filename	4033519*NM-BENCH.
Element/Vers	LTEST
Storage	167 words
Timing	unknown
Consultant	None

REFERENCE NWC TM 2410



NAME LTGIVN

PURPOSE To generate the Givens test matrix of order  $N$  and its exact inverse.

USAGE CALL LTGIVN (G, GI, N, NN)

G.....Test matrix - ( $N, N$ )	Output
GI....Exact inverse of G	Output
N.....Order of G	Input
NN....Row dimension of G	Input

ACCESS LIB NWC\*MATHLIB.

ERRORS None

REMARKS None

PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Certified, Fully Supported by CCF
Entry Names	LTGIVN
External Refs	NERR3\$
Filename	NWC*MATHLIB
Element/Vers	LTGIVN
Storage	198 words
Timing	unknown
Consultant	L. W. Lucas, Ext. 3561

TESTING Output from LTGIVN was handchecked against Gregory and Karney.

METHOD The Givens test matrix  $G_n$  and its inverse are defined by

$$G_n = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & 3 & & & \\ & & \ddots & & \\ 1 & 3 & 5 & \dots & 2n-1 \end{bmatrix}$$

$$G_n^{-1} = \frac{1}{2} \begin{bmatrix} 3 & -1 & & & \\ -1 & 2 & & & \\ & & \ddots & & \\ & & & 2 & 1 \\ & & & 1 & 1 \end{bmatrix}$$

REFERENCE Gregory and Karney. *A Collection of Matrices for Testing Computational Algorithms*. Wiley-Interscience, 1969.

NAME LTHILB

PURPOSE To generate the inverse Hilbert test matrix of order  $N$  and its exact inverse (Hilbert matrix)

USAGE CALL LTHILB (T, H, N, NN)

T.....Inverse Hilbert matrix - ( $N, N$ )	Output
H.....Hilbert matrix	Output
N.....Order of T, H	Input
NN....Row dimension of T, H	Input

ACCESS LIB NWC\*MATHLIB.

ERRORS None

REMARKS The inverse Hilbert matrix is used as a test matrix since its elements are integers. Due to integer overflow in computing the elements of T, the maximum usable value of  $N$  is 7. The elements of H are computed using double precision arithmetic and are exact to single precision.

## PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Certified, Fully Supported by CCF
Entry Names	LTHILB
External Refs	NERR3\$
Filename	NWC*MATHLIB
Element/Vers	LTHILB
Storage	254 words
Timing	unknown
Consultant	L. W. Lucas, Ext. 3561

TESTING Output from LTHILB was handchecked against Gregory and Karney.

METHOD The algorithm for computing the elements of T is given in Forsythe-Moler, p. 85. The formula defining H is

$$H = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \dots & \frac{1}{n} \\ \frac{1}{2} & \frac{1}{3} & & & \\ \frac{1}{3} & & \ddots & & \\ \vdots & & & \ddots & \\ \frac{1}{n} & & & & \frac{1}{2n-1} \end{bmatrix}$$

24

REFERENCES

Gregory and Karney  
*A Collection of Matrices for Testing Computational Algorithms*  
 Wiley-Interscience, 1969

Forsythe and Moler  
*Computer Solution of Linear Algebraic Systems*  
 Prentice-Hall, 1967



NAME LTNEWT

PURPOSE To generate Newman-Todd test matrix of order  $N$  and its exact inverse.

USAGE CALL LTNEWT (A, AI, N, NN)

A.....Newman-Todd test matrix - ( $N, N$ )	Output
AI....Exact inverse of A	Output
N.....Order of A	Input
NN....Row dimension of A, AI	Input

ACCESS LIB NWC\*MATHLIB

ERRORS None

REMARKS Since  $A$  is orthogonal,  $AI$  is set equal to the transpose of  $A$ . The computations are done in double precision, since the elements of  $A$  are not exactly representable in single precision.

PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Certified, Fully Supported by CCF
Entry Names	LTNEWT
External Refs	DSQRT, DSIN, NERR3\$
Filename	NWC*MATHLIB
Element/Vers	LTNEWT
Storage	142 words
Timing	unknown
Consultant	L. W. Lucas, Ext. 3561.

TESTING Output from LTNEWT was handchecked against Gregory and Karney.

METHOD The Newman-Todd test matrix  $A$  is defined by

$$A = (a_{ij}), \quad a_{ij} = \frac{2}{n+1} \sin \left( \frac{ij\pi}{n+1} \right)$$

REFERENCE Gregory and Karney  
*A Collection of Matrices for Testing Computational Algorithms*  
 Wiley-Interscience, 1969

NAME LTPEI

PURPOSE To generate Pei test matrix of order  $N$  with parameter  $S$  and its exact inverse.

USAGE CALL LTPEI (P, Q, N, NN, S)

P.....Pei test matrix - ( $N, N$ )	Output
Q.....Exact inverse of P	Output
N.....Order of P, Q	Input
NN.....Row dimension of P, Q	Input
S.....Pei parameter	Input

ACCESS LIB NWC\*MATHLIB.

ERRORS None

REMARKS The elements of P are integers and are exact to single precision. The elements of Q are fractions and are computed in double precision. The parameter  $S$  can be used to vary the condition number of P.

## PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Certified, Fully Supported by CCF
Entry Names	LTPEI
External Refs	NERR3\$
Filename	NWC*MATHLIB
Element/Vers	LTPEI
Storage	183 words
Timing	unknown
Consultant	L. W. Lucas, Ext. 3561

TESTING Output from LTPEI was handchecked against Gregory and Karney.

METHOD The formulas defining  $P$  and  $Q$ , taken from Gregory-Karney, are

$$P = (p_{ij}) \quad p_{ij} = \begin{cases} 1 + s & i = j \\ 1 & i \neq j \end{cases}$$

$$Q = (q_{ij}) \quad q_{ij} = \begin{cases} \frac{s + n - 1}{s(s + n)} & i = j \\ -\frac{1}{s(s + n)} & i \neq j \end{cases}$$

where  $s$  is the Pei parameter.

REFERENCE Gregory and Karney  
A Collection of Matrices for Testing Computational  
Algorithms  
Wiley-Interscience, 1969



NAME	LTPRNT	
PURPOSE	To print summary test results for LEQTST	
USAGE	CALL LTHDG (IW) IW.....Unit number for printout CALL LTPRNT (IW, NAME, N, IER, TIME, COND, ERR) IW.....Unit number for printout NAME...Name of test matrix N.....Order of test matrix IER....Error return from candidate routine TIME...Time to compute inverse COND...Logarithm of condition number ERR....Array of error measures	
		Input Input Input Input Input Input Input
ACCESS	IN 4033519*NM-BENCH.LTPRNT	
ERRORS	None	
REMARKS	NAME is a 12-character hollerith string giving the name of the test matrix. Entry LTPRNT is used to print summary test results. Entry LTHDG is used to print headings for the summary test results.	
PROGRAM INFO		
	Machine	UNIVAC 1110
	Language	FORTRAN
	Author	L. W. Lucas, Code 4033 NWC
	Date	14 March 1975
	Status	Unsupported
	Entry Names	LTHDG, LTPRNT
	External Refs	NWDU\$, NIØ1\$, NIØ2\$, NERR3\$
	Filename	4033519*NM-BENCH
	Element/Vers	LTPRNT
	Storage	108 words
	Timing	unknown
	Consultant	None
REFERENCE	NWC TM 2410	

89

NAME	LTRITE	
PURPOSE	To write matrices for LEQTST	
USAGE	CALL LTRITE (IW, A, X, AI, E, R, N, NN)	
	IW.....Logical unit number for output	Input
	A.....Test matrix - (N, N)	Input
	X.....Computed inverse	Input
	AI.....Exact inverse	Input
	E.....Error matrix	Input
	R.....Residual matrix	Input
	N.....Order of matrices	Input
	NN.....Row dimension of arrays	Input
ACCESS	IN 4033519*NM-BENCH.LTRITE	
ERRORS	None	
REMARKS	None	
PROGRAM INFO		
	Machine	UNIVAC 1110
	Language	FORTRAN
	Author	L. W. Lucas, Code 4033 NWC
	Date	14 March 1975
	Status	Unsupported
	Entry Names	LTRITE
	External Refs	MXRITE, NERR3\$
	Filename	4033519*NM-BENCH
	Element/Vers	LTRITE
	Storage	96 words
	Timing	unknown
	Consultant	None
REFERENCE	NWC TM 2410	

NAME LTRUTH

PURPOSE To generate Rutishauser test matrix of order  $N$  and its exact inverse.

USAGE CALL LTRUTH (R, RI, N, NN, JR)

R....Rutishauser test matrix - ( $N, N$ )	Output
RI....Exact inverse of R	Output
N....Order of R, RI	Input
NN....Row dimension of R, RI	Input
JR....Work space array of length $N$	Scratch

ACCESS LIB NWC\*MATHLIB.

ERRORS None

REMARKS The scratch array JR is used to store the  $j$ th column of R, while generating the  $j+1$ -th column via a recursion formula. R is its own inverse, so RI is just a copy of R.

PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Certified, Fully Supported by CCF
Entry Names	LTRUTH
External Refs	NERR3\$
Filename	NWC*MATHLIB
Element Vers	LTRUTH
Storage	197 words
Timing	unknown
Consultant	L. W. Lucas, Ext. 3561

TESTING Output from LTRUTH was handchecked against Gregory and Karney.

METHOD The Rutishauser test matrix is defined by

$$R = \begin{bmatrix} 1 & & & & 0 \\ 1 & -1 & & & \\ 1 & -2 & 1 & & \\ \vdots & & & \ddots & \\ 1 & -n+1 & & & (-1)^{n-1} \end{bmatrix}$$



The columns of  $R$  are, except for sign, the diagonals in Pascal's triangle. Thus, the following recursion formula can be used to generate the elements of  $R$ .

$$r_{ij} = \begin{cases} 0 & i < j \\ r_{i-1, j} - r_{i-1, j-1} & i \geq j \end{cases}$$

## REFERENCE

Gregory and Karney  
*A Collection of Matrices for Testing Computational Algorithms*  
Wiley-Interscience, 1969

NAME	LTWILK	
PURPOSE	To generate Wilkinson test matrix of order 6 and its exact inverse.	
USAGE	CALL LTWILK (W, V, N, NN)	
	W.....Wilkinson test matrix	Output
	V.....Exact inverse of W	Output
	N.....Order of W, V	Output
	NN....Row dimension of W, V	Input
ACCESS	LIB NWC*MATHLIB.	
ERRORS	None	
REMARKS	N is set equal to 6 by LTWILK.	
PROGRAM INFO		
	Machine	UNIVAC 1110
	Language	FORTRAN
	Author	L. W. Lucas, Code 4033 NWC
	Date	14 March 1975
	Status	Certified, Fully Supported by CCF
	Entry Names	LTWILK
	External Refs	NERR3\$
	Filename	NWC*MATHLIB
	Element/Vers	LTWILK
	Storage	165 words
	Timing	unknown
	Consultant	L. W. Lucas, Ext. 3561
TESTING	Output from LTWILK was handchecked against Gregory and Karney.	
METHOD	The internal arrays X and Y are initialized to the Wilkinson test matrix, and its exact inverse, respectively, which are given in the reference. These are then copied into W and V, respectively, upon entry to LTWILK.	
REFERENCE	Gregory and Karney <i>A Collection of Matrices for Testing Computational Algorithms</i> Wiley-Interscience, 1969	

NAME MXRITE

PURPOSE To write out a general matrix, preceded by a title.

USAGE CALL MXRITE (IW, A, N, M, NN, TITLE)

IW.....	Logical unit number for printout	Input
A.....	The matrix (N, M)	Input
N.....	Rows in A	Input
M.....	Columns in A	Input
NN.....	Row dimension of A	Input
TITLE..	Title printed above A	Input

ACCESS NWC\*MATHLIB.

ERRORS None

REMARKS TITLE is an 18-character hollerith string printed above A. The matrix is printed out 8 columns across the page. Remaining columns are printed below, again 8 columns across the page.

PROGRAM INFO

Machine	UNIVAC 1110
Language	FORTRAN
Author	L. W. Lucas, Code 4033 NWC
Date	14 March 1975
Status	Certified, Fully Supported by CCF
Entry Names	MXRITE
External Refs	NWDU\$, NI01\$, NI02\$, NERR3\$
Filename	NWC*MATHLIB
Element/Vers	MXRITE
Storage	167 words
Timing	unknown
Consultant	L. W. Lucas, Ext. 3561

REFERENCE None



REFERENCES

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